
Lab4. Interrupt

Applications using Switch/Timer
Interrupt Drivers

fpga_int0 driver (1)

```
module_init(init_module2);
module_exit(close_module2);

struct file_operations FPGA_INT0_PS_Reg_FOPS =
{
    .owner = THIS_MODULE,
    .open = fpga_int0_ps_reg_open,
    .write = fpga_int0_ps_reg_write,
    .read = fpga_int0_ps_reg_read,
};

int init_module2(void)
{
    int FPGA_DEV;
    FPGA_DEV = register_chrdev(FPGA_INT0_MAJOR_NUMBER, FPGA_INT0_DRIVER_NAME,
    &FPGA_INT0_PS_Reg_FOPS);
    if(FPGA_DEV < 0)
    {
        printk(KERN_WARNING "Can't get any major\n");
        return FPGA_DEV;
    }
    fpga_int0_ps_reg_major = FPGA_INT0_MAJOR_NUMBER;
    fpga_int0_ps_reg_addr = ioremap(FPGA_INT0_PS_Reg_ADDRESS,0x2);
    printk("init module, %s major
    number: %d\n",FPGA_INT0_DRIVER_NAME,fpga_int0_ps_reg_major);
}
```

fpga_int0 driver (2)

```
set_irq_type(IRQ_GPIO(83),IRQT_FALLING);
if(request_irq(IRQ_GPIO(83),fpga_int0_interrupt,SA_INTERRUPT,FPGA_INT0_DRIVER_NAME,NULL))
{
    printk("FPGA INT 0 Interrupt init fail...!\n");
}
return 0;
}

void close_module2(void)
{
    if(unregister_chrdev(fpga_int0_ps_reg_major,FPGA_INT0_DRIVER_NAME))
    {
        printk(KERN_WARNING "%s DRIVER CLEANUP FAILED\n",
FPGA_INT0_DRIVER_NAME);
    }
}

int fpga_int0_ps_reg_open(struct inode *fpga_int0_ps_reg_inode, struct file
*fpga_int0_ps_reg_file)
{
    return 0;
}
```

fpga_int0 driver (3)

```
irqreturn_t fpga_int0_interrupt(int irq,void *dev_id,struct pt_regs *regs)
```

```
{  
    printk("FPGA INT 0 Interrupt Success\n");  
    kill_proc(PID_ID,SIGUSR1,1);  
    return IRQ_HANDLED;  
}
```

```
ssize_t fpga_int0_ps_reg_write(struct file *fpga_int0_ps_reg_inode,int *gdata, size_t length,  
    loff_t *off_what)
```

```
{  
    PID_ID = *gdata;  
    return length;  
}
```

```
ssize_t fpga_int0_ps_reg_read(struct file *fpga_int0_ps_reg_inode,int *gdata, size_t length,  
    loff_t *off_what)
```

```
{  
    *gdata = inw(fpga_int0_ps_reg_addr);  
    copy_to_user(gdata,gdata,sizeof(gdata));  
    return length;  
}
```

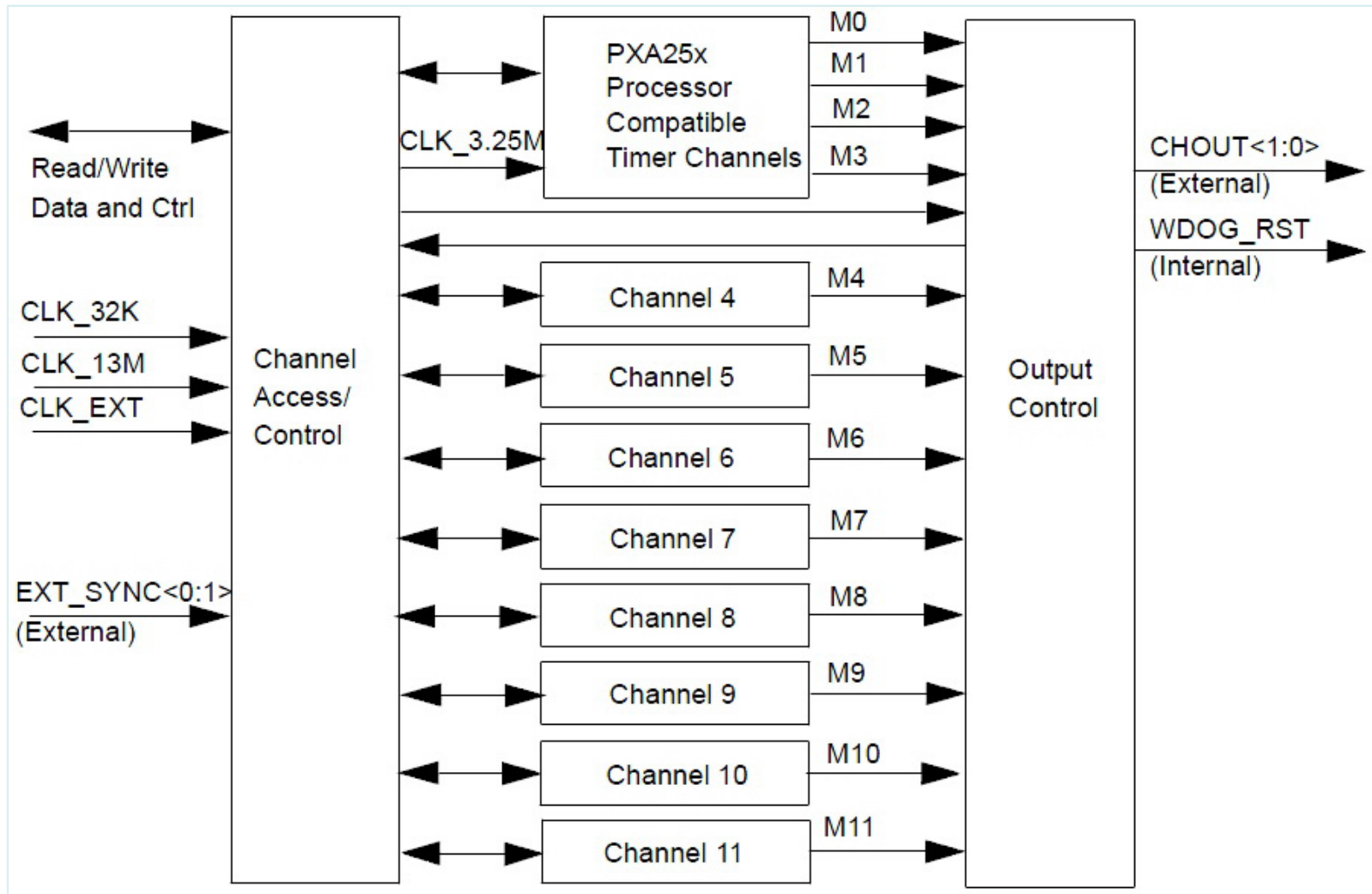
fpga_int0 application (1)

```
int INT0_DEV;  
int INT0_DEV_PID;  
int temp = 0;  
  
void usrsignal(int sig)  
{  
    read(INT0_DEV,&temp,sizeof(temp));  
    switch(temp)  
    {  
        case 0x001: if(temp == 0x001) printf("Push SW1\n"); break;  
        case 0x002: if(temp == 0x002) printf("Push SW2\n"); break;  
        case 0x004: if(temp == 0x004) printf("Push SW3\n"); break;  
        case 0x008: if(temp == 0x008) printf("Push SW4\n"); break;  
        case 0x010: if(temp == 0x010) printf("Push SW5\n"); break;  
        case 0x020: if(temp == 0x020) printf("Push SW6\n"); break;  
        case 0x040: if(temp == 0x040) printf("Push SW7\n"); break;  
        case 0x080: if(temp == 0x080) printf("Push SW8\n"); break;  
        case 0x100: if(temp == 0x100) printf("Push SW9\n"); break;  
        case 0x200: if(temp == 0x200) printf("Push SW10\n"); break;  
        case 0x400: if(temp == 0x400) printf("Push SW11\n"); break;  
        case 0x800: if(temp == 0x800) printf("Push SW12\n"); break;  
        default : printf(" What ? \n"); break;  
    }  
}
```

fpga_int0 application (2)

```
int main(void)
{
    system("clear");
    INT0_DEV = open("/dev/fpga_int0",O_RDWR);
    if(INT0_DEV < 0)
    {
        printf(" driver open fail\n");
        return -1;
    }
    (void)signal(SIGUSR1,usrsignal);
    INT0_DEV_PID = getpid();
    write(INT0_DEV,&INT0_DEV_PID,sizeof(INT0_DEV_PID));
    printf("int0_test\n");
    printf("stop = Ctrl+C\n");
    while(1)
    {
    }
    close(INT0_DEV);
    return 0;
}
```

Operating System Timers



ostimer driver (1)

```
#define DEVICE_NAME "ostimer"
#define OSTIMER_MAJOR    252

static int Major;
static int Device_Open = 0;
static int app_id;

static irqreturn_t ostimer_handler1(int irq, void *dev_id, struct pt_regs *regs )
{
    kill_proc(app_id,SIGUSR2,1);
    OSSR |= XLLP_OSSR_M4;
    return IRQ_HANDLED;
}
static int ostimer_ioctl(struct inode *inode, struct file *file,
                        unsigned int cmd,unsigned long gdata)
{
    int id;
    copy_from_user(&id,(char *)gdata,4);
    app_id = id;
    return 0;
}
```


Table 22-10. OSSR Bit Definitions

0x40A0_0014				OSSR								OS Timer																				
User Settings	[Bit fields 31-0]																															
Bit	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	reserved																				M11	M10	M9	M8	M7	M6	M5	M4	M3	M2	M1	M0
Reset	?	?	?	?	?	?	?	?	?	?	?	?	?	?	?	?	?	?	?	?	0	0	0	0	0	0	0	0	0	0	0	0
Bits	Access		Name		Description																											
31:12	reserved		—		reserved																											
11:0	R/W		M{n}		Match Status Channel <i>n</i> If OIER(<i>n</i>) is set then: 0 = No OSMR _{<i>n</i>} match has occurred since the last clear. 1 = An OSMR _{<i>n</i>} match has occurred since the last clear.																											

ostimer driver (2)

```
ssize_t ostimer_write (struct file *file,
                      const char *buffer, /* buffer */
                      size_t length,      /* length of buffer */
                      loff_t * offset)    /* offset in the file */
{
    return (length);
}
static struct file_operations led_fops =
{
    open:          ostimer_open,
    write:         ostimer_write,
    release:       ostimer_release,
    ioctl:        ostimer_ioctl,
};
static int __init ostimer_init(void)
{
    /*
    * Register the character device
    */
    int return_val1;
    Major = register_chrdev (OSTIMER_MAJOR, DEVICE_NAME, &led_fops);
    if (Major < 0) {
        printk ("ostimer init_module: failed with %d\n", OSTIMER_MAJOR);
        return Major;
    }
    printk ("ostimer driver registred: major = %d\n", OSTIMER_MAJOR);
}
```

ostimer driver (3)

```
OMCR4 |= XLLP_OMCR_CRES_1MSEC;
OSMR4 = 9;
OMCR4 |= XLLP_OMCR_C;
OMCR4 |= XLLP_OMCR_P;
OMCR4 |= XLLP_OMCR_R;
OIER |= XLLP_OIER_E4;
OSCR4 = 0; /* start OS timer 4 */

set_irq_type( IRQ_OST_4_11, IRQT_FALLING );
return_val1 = request_irq(IRQ_OST_4_11, ostimer_handler1, SA_INTERRUPT, "ostimer INT",
    NULL );
if( return_val1 < 0 ) {
    printk(KERN_ERR "Acumen270_push_init() : Can't request irq %#010x\n",
        IRQ_OST_4_11);
    return -1;
}
return 0;
}

module_init(ostimer_init);
module_exit(ostimer_exit);
```

ostimer application (1)

```
int I_LED_DEV;
unsigned int counter = 0;

void usrsignal(int sig)
{   int temp = 31;
    counter++;
    if (counter >= 100) counter=0;
    if (counter == 0)
    {
        printf("On\n");
        temp=0;write(I_LED_DEV,&temp,sizeof(temp));
    }
    if (counter == 50)
    {
        printf("Off\n");
        temp=0xff;write(I_LED_DEV,&temp,sizeof(temp));
    }
}
```

ostimer application (2)

```
int main(void)
{
    int fd,id;
    unsigned char c;
    I_LED_DEV = open("/dev/fpga_led",O_RDWR);
    if(I_LED_DEV < 0)
    {
        printf(" fpga_led driver open fail\n");
        return -1;
    }
    fd = open("/dev/ostimer",O_WRONLY);
    if (fd < 0){
        printf("ostimer Device Open Error\n");
        exit(1);
    }
    (void)signal(SIGUSR2,usrsignal);
    id = getpid();
    ioctl(fd,0,&id,4);
    for(;;){}
    close(fd);
}
```

Lab5. Digital Clock on Embedded Linux

Applications using Switch/Timer
Interrupt Drivers

Exercise(1)

- **1/100 초를 나타낼 수 있는 디지털 시계를 만든다.**
- 현재 시각은 **8자리 (시,분,초,1/00초 각 2자리씩)**로 나타낸다.
- 프로그램이 시작되면 “**Enter Time**” 메시지를 LCD에 내보낸 후 초기 설정 시각의 입력을 기다린다.
- 초기 시각은 **8자리 (시,분,초,1/00초 각 2자리씩)**로 1번 부터 **10번**까지의 버튼 키를 이용하여 입력한다.(숫자 **0**은 **10번** 버튼 사용) 한자리씩 입력할 때 마다 입력된 숫자가 **seven segment display**에 나타나야 한다. 새로 누른 숫자는 가장 오른쪽 자리에 나타나며, 다음 숫자를 누르면 왼쪽으로 한자리씩 이동한다. 버튼 누르는 횟수에 관계 없이 숫자는 계속 나타나야 한다. **Enter Key(11번 버튼)**를 누르면 초기 시각 입력이 끝나고 시계가 가기 시작한다.

Exercise(2)

- 시계가 가는 동안은 “**Running**” 메시지가 **LCD**에 나타난다.
- 시계가 가는 중 **12**번 버튼 키를 누르면 시계가 정지되고 “**Stopped**” 메시지가 **LCD**에 나타난다. 다시 **12**번 버튼 키를 누르면 “**Running**” 메시지가 **LCD**에 나타나고 시계가 간다.
- 시계가 가는 동안 **11**번 버튼 키를 누르면 시계가 정지되고 “**Enter Time**” 메시지를 **LCD**에 내보낸 후 초기 설정 시각의 입력을 기다린다.
- 적어도 **2**개 이상의 **thread**를 사용한다.